

Pole Diagrams

1. Definition of the Pole Diagram

The **pole diagram** of a function $F(s)$ is simply the complex s -plane with an **X** marking the location of each pole of $F(s)$.

Example 1. Draw the pole diagrams for each of the following functions.

a) $F_1(s) = \frac{1}{s+2}$

b) $F_2(s) = \frac{1}{s-2}$

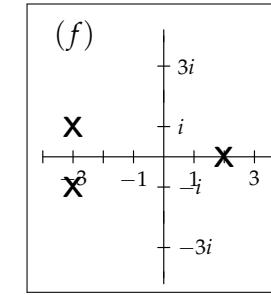
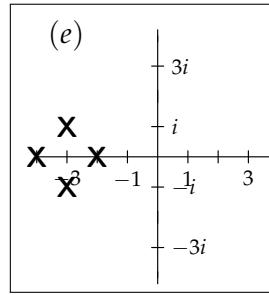
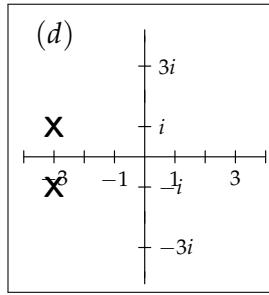
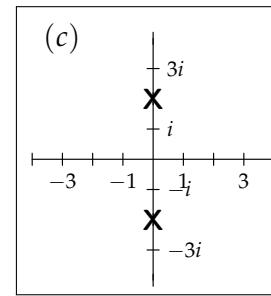
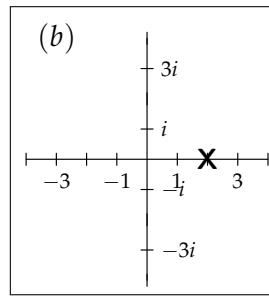
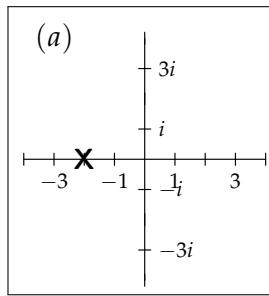
c) $F_3(s) = \frac{1}{s^2+4}$

d) $F_4(s) = \frac{s}{s^2+6s+10}$

e) $F_5(s) = \frac{1}{((s^2+3)^2+1)(s+2)(s+4)}$

f) $F_6(s) = \frac{1}{((s+3)^2+1)(s-2)}$

Solution.



For (d) we found the poles by first completing the square: $s^2 + 6s + 10 = (s + 3)^2 + 1$, so the poles are at $s = -3 \pm i$.

Example 2. Use the pole diagram to determine the exponential growth rate of the inverse Laplace transform of each of the functions in example 1.

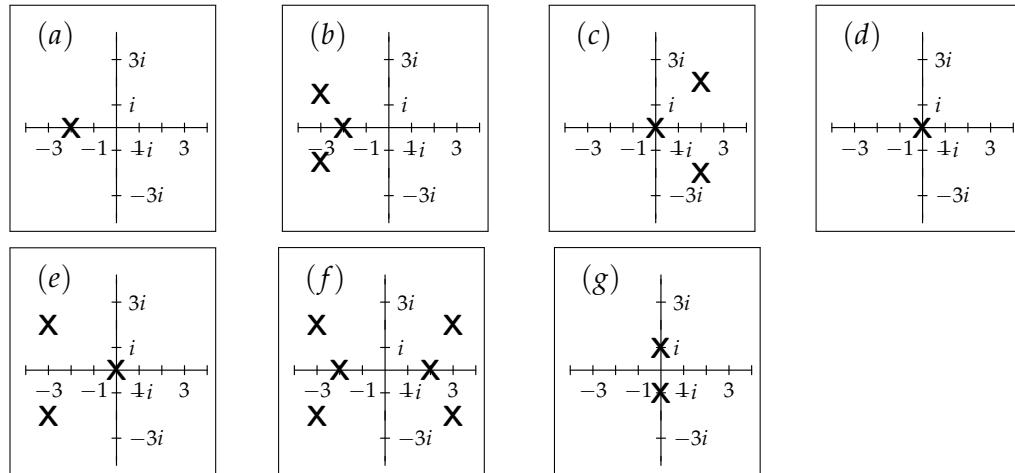
Solution.

- The largest pole is at -2, so the exponential growth rate is -2.
- The largest pole is at 2, so the exponential growth rate is 2.
- The poles are $\pm 2i$, so the largest real part of a pole is 0. The exponential growth rate is 0.
- The largest real part of a pole is -3. The exponential growth rate is -3.
- The largest real part of a pole is -2. The exponential growth rate is -2.

f) The largest real part of a pole is 2. The exponential growth rate is 2.

Example 3. Each of the pole diagrams below is for a function $F(s)$ which is the Laplace transform of a function $f(t)$. Say whether

- (i) $f(t) \rightarrow 0$ as $t \rightarrow \infty$
- (ii) $f(t) \rightarrow \infty$ as $t \rightarrow \infty$
- (iii) You don't know the behavior of $f(t)$ as $t \rightarrow 0$,



Solution. a) Exponential growth rate is -2, so $f(t) \rightarrow 0$.

b) Exponential growth rate is -2, so $f(t) \rightarrow 0$.

c) Exponential growth rate is 2, so $f(t) \rightarrow \infty$.

d) Exponential growth rate is 0, so we can't tell how $f(t)$ behaves.

Two examples of this: (i) if $F(s) = 1/s$ then $f(t) = 1$, which stays bounded; (ii) if $F(s) = 1/s^2$ then $f(t) = t$, which does go to infinity, but more slowly than any positive exponential.

e) Exponential growth rate is 0, so don't know the behavior of $f(t)$.

f) Exponential growth rate is 3, so $f(t) \rightarrow \infty$.

g) Exponential growth rate is 0, so don't know the behavior of $f(t)$. (e.g. both $\cos t$ and $t \cos t$ have poles at $\pm i$.)

2. The Pole Diagram for an LTI System

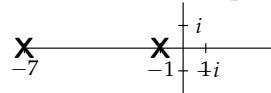
Definition: The pole diagram for an LTI system is defined to be the pole diagram of its transfer function.

Example 4. Give the pole diagram for the system

$$\ddot{x} + 8\dot{x} + 7x = f(t),$$

where we take $f(t)$ to be the input and $x(t)$ the output.

Solution. The transfer function for this system is $W(s) = \frac{1}{s^2 + 8s + 1} = \frac{1}{(s + 1)(s + 7)}$. Therefore, the poles are $s = -1, -7$ and the pole diagram is



Example 5. Give the pole diagram for the system

$$\ddot{x} + 4\dot{x} + 6x = \dot{y},$$

where we consider $y(t)$ to be the input and $x(t)$ to be the output.

Solution. Assuming rest IC's, Laplace transforming this equation gives us $(s^2 + 4s + 6)X = sY$. This implies $X(s) = \frac{s}{s^2 + 4s + 6}Y(s)$ and the transfer function is $W(s) = \frac{s}{s^2 + 4s + 6}$. This has poles at $s = -2 \pm \sqrt{2}i$.

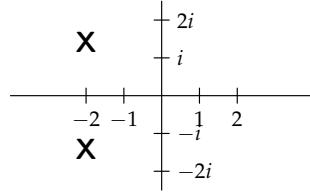


Figure: Pole diagram for the system in example 5.

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18.03SC Differential Equations

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